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# Lecture 10

## Sorting

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Bringing Order to the World

# Lecture Outline

- Iterative sorting algorithms (comparison based)
  - Selection Sort
  - Bubble Sort
  - Insertion Sort
- Recursive sorting algorithms (comparison based)
  - Merge Sort
  - Quick Sort
- Radix sort (non-comparison based)
- Properties of Sorting
  - In-place sort, stable sort
  - Comparison of sorting algorithms
- Note: we only consider sorting data in **ascending order**

# Why Study Sorting?

- When an input is sorted, many problems become easy (e.g. **searching**, **min**, **max**, **k-th smallest**)
- Sorting has a variety of interesting algorithmic solutions that embody many ideas
  - Comparison vs non-comparison based
  - Iterative
  - Recursive
  - Divide-and-conquer
  - Best/worst/average-case bounds
  - Randomized algorithms

# Applications of Sorting

- Uniqueness testing
- Deleting duplicates
- Prioritizing events
- Frequency counting
- Reconstructing the original order
- Set intersection/union
- Finding a target pair  $x, y$  such that  $x+y = z$
- Efficient searching

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# Selection Sort

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# Selection Sort: Idea

- Given an array of  $n$  items
  1. Find the largest item  $x$ , in the range of  $[0 \dots n-1]$
  2. Swap  $x$  with the  $(n-1)^{\text{th}}$  item
  3. Reduce  $n$  by 1 and go to Step 1

# Selection Sort: Illustration

29	10	14	37	13
----	----	----	----	----

**37** is the largest, swap it with the last element, i.e. **13**.

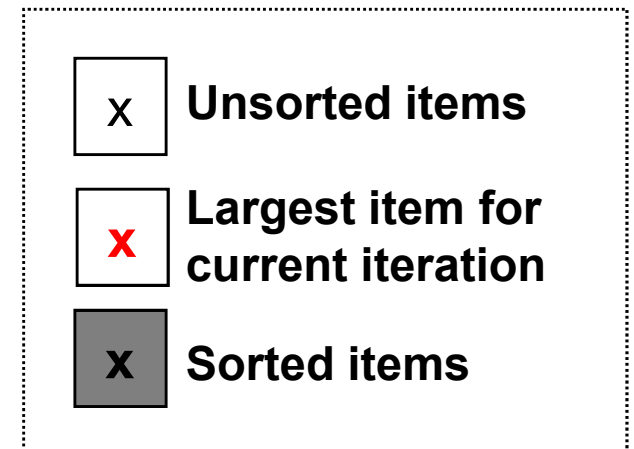
Q: How to find the largest?

29	10	14	13	37
----	----	----	----	----

13	10	14	29	37
----	----	----	----	----

13	10	14	29	37
----	----	----	----	----

10	13	14	29	37
----	----	----	----	----



**Sorted!**

We can also find the smallest and put it the front instead

<http://visualgo.net/sorting?create=29,10,14,37,13&mode=Selection>

# Selection Sort: Implementation

```
void selectionSort(int a[], int n) {  
    for (int i = n-1; i >= 1; i--) {  
        int maxIdx = i;  
        for (int j = 0; j < i; j++)  
            if (a[j] >= a[maxIdx])  
                maxIdx = j;  
        // swap routine is in STL <algorithm>  
        swap(a[i], a[maxIdx]);  
    }  
}
```

**Step 1:**  
Search for  
maximum  
element

**Step 2:**  
Swap  
maximum  
element  
with the last  
item i



# Selection Sort: Analysis

```
void selectionSort(int a[], int n) {  
    for (int i = n-1; i >= 1; i--) {  
        int maxIdx = i;  
        for (int j = 0; j < i; j++)  
            if (a[j] >= a[maxIdx])  
                maxIdx = j;  
        // swap routine is in STL <algorithm>  
        swap(a[i], a[maxIdx]);  
    }  
}
```

Number of times  
executed

■  $n-1$

■  $n-1$

■  $(n-1)+(n-2)+\dots+1$   
=  $n(n-1)/2$

■  $n-1$

Total

=  $c_1(n-1) +$   
 $c_2 * n * (n-1)/2$   
=  $O(n^2)$

- $c_1$  and  $c_2$  are cost of statements in outer and inner blocks

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# Bubble Sort

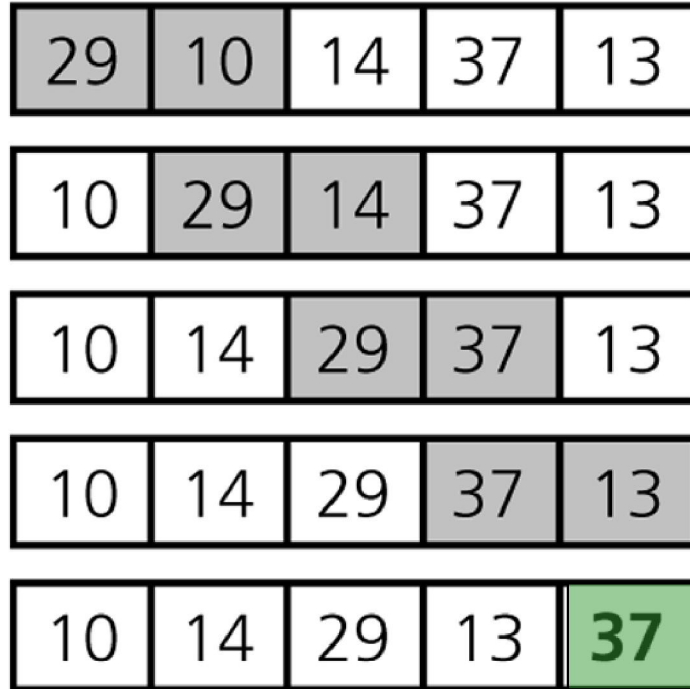
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# Bubble Sort: Idea

- Given an array of  $n$  items
  1. Compare pair of adjacent items
  2. Swap if the items are out of order
  3. Repeat until the end of array
    - The largest item will be at the last position
  4. Reduce  $n$  by 1 and go to Step 1
  
- Analogy
  - Large item is like “bubble” that floats to the end of the array

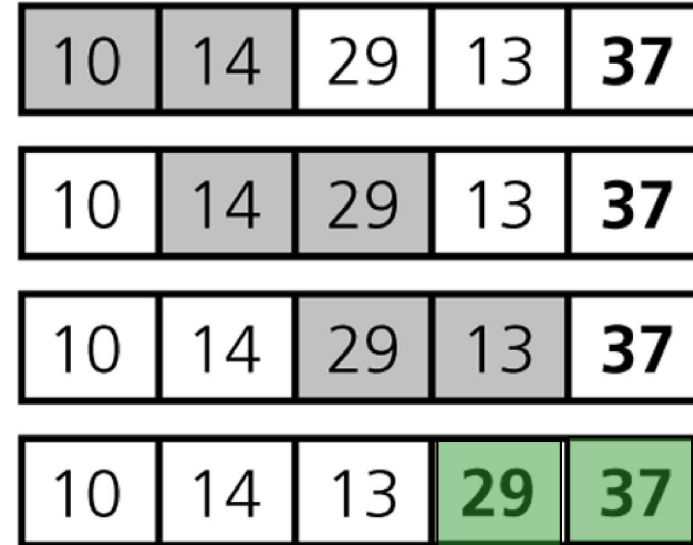
# Bubble Sort: Illustration

(a) Pass 1



At the end of **Pass 1**, the largest item **37** is at the last position.

(b) Pass 2



At the end of **Pass 2**, the second largest item **29** is at the second last position.



# Bubble Sort: Implementation

```
void bubbleSort(int a[], int n) {  
    for (int i = n-1; i >= 1; i--) {  
        for (int j = 1; j <= i; j++) {  
            if (a[j-1] > a[j])  
                swap(a[j], a[j-1]);  
        }  
    }  
}
```

**Step 1:**  
Compare  
adjacent  
pairs of  
numbers

**Step 2:**  
Swap if the  
items are out  
of order

29	10	14	37	13
----	----	----	----	----

<http://visualgo.net/sorting?create=29,10,14,37,13&mode=Bubble>

# Bubble Sort: Analysis

- 1 iteration of the inner loop (test and swap) requires time bounded by a constant  $c$
- Two nested loops
  - Outer loop: exactly  $n$  iterations
  - Inner loop:
    - when  $i=0$ ,  $(n-1)$  iterations
    - when  $i=1$ ,  $(n-2)$  iterations
    - ...
    - when  $i=(n-1)$ ,  $0$  iterations
- Total number of iterations =  $0+1+\dots+(n-1) = n(n-1)/2$
- Total time =  $c n(n-1)/2 = \mathbf{O}(n^2)$

# Bubble Sort: Early Termination

- Bubble Sort is inefficient with a  $O(n^2)$  time complexity
- However, it has an interesting property
  - Given the following array, how many times will the inner loop swap a pair of item?

3	6	11	25	39
---	---	----	----	----

- Idea
  - If we go through the inner loop with no swapping
    - ➔ the array is sorted
    - ➔ can stop early!

# Bubble Sort v2.0: Implementation

```
void bubbleSort2(int a[], int n) {  
    for (int i = n-1; i >= 1; i--) {  
        bool is_sorted = true;  
        for (int j = 1; j <= i; j++) {  
            if (a[j-1] > a[j]) {  
                swap(a[j], a[j-1]);  
                is_sorted = false;  
            }  
        } // end of inner loop  
        if (is_sorted) return;  
    }  
}
```

Assume the array is sorted before the inner loop

Any swapping will invalidate the assumption

If the flag remains **true** after the inner loop → sorted!



# Bubble Sort v2.0: Analysis

- Worst-case

- Input is in descending order
- Running time remains the same:  $O(n^2)$

- Best-case

- Input is already in ascending order
- The algorithm returns after a single outer iteration
- Running time:  $O(n)$

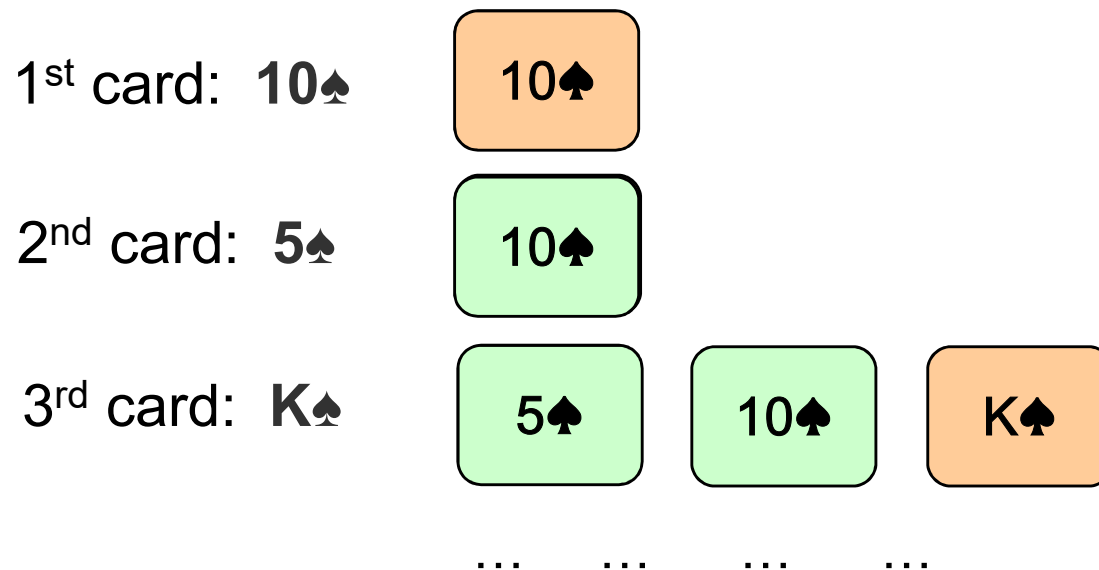
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# Insertion Sort

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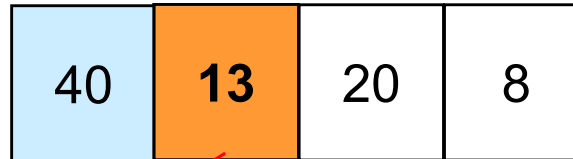
# Insertion Sort: Idea

- Similar to how most people arrange a hand of poker cards
  - Start with one card in your hand
  - Pick the next card and insert it into its proper sorted order
  - Repeat previous step for all cards

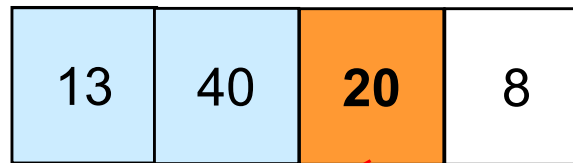


# Insertion Sort: Illustration

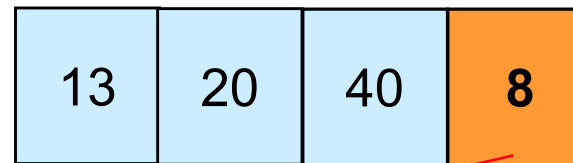
Start



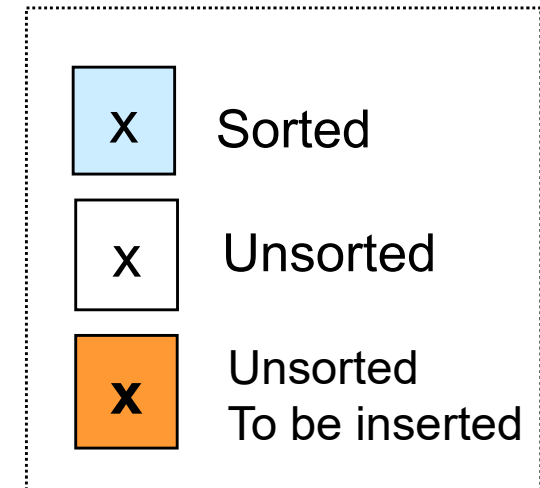
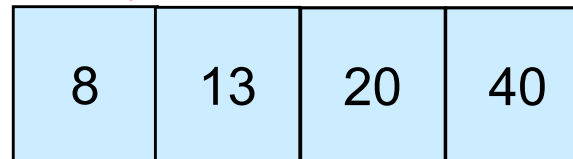
Iteration 1



Iteration 2



Iteration 3



<http://visualgo.net/sorting?create=40,13,20,8&mode=Insertion>

# Insertion Sort: Implementation

```
void insertionSort(int a[], int n) {  
    for (int i = 1; i < n; i++) {  
        int next = a[i];  
        int j;  
  
        for (j = i-1; j >= 0 && a[j] > next; j--)  
            a[j+1] = a[j];  
  
        a[j+1] = next;  
    }  
}
```

**next** is the item to be inserted

Shift sorted items to make place for **next**

Insert **next** to the correct location

29	10	14	37	13
----	----	----	----	----

<http://visualgo.net/sorting?create=29,10,14,37,13&mode=Insertion>

# Insertion Sort: Analysis

- Outer-loop executes  $(n-1)$  times
- Number of times inner-loop is executed depends on the input
  - **Best-case:** the array is already sorted and  $(a[j] > \text{next})$  is always false
    - No shifting of data is necessary
  - **Worst-case:** the array is reversely sorted and  $(a[j] > \text{next})$  is always true
    - Insertion always occur at the front
- Therefore, the **best-case** time is  $O(n)$
- And the **worst-case** time is  $O(n^2)$

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# Merge Sort

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# Merge Sort: Idea

- Suppose we only know how to merge two sorted sets of elements into one
  - Merge  $\{1, 5, 9\}$  with  $\{2, 11\}$   $\rightarrow$   $\{1, 2, 5, 9, 11\}$
- Question
  - Where do we get the two sorted sets in the first place?
- Idea (use **merge** to sort  $n$  items)
  - Merge each pair of elements into sets of 2
  - Merge each pair of sets of 2 into sets of 4
  - Repeat previous step for sets of 4 ...
  - Final step: merge 2 sets of  $n/2$  elements to obtain a fully sorted set



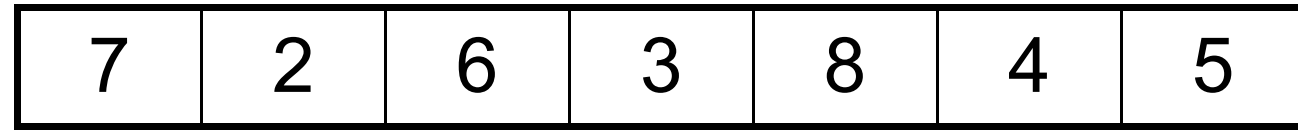
# Divide-and-Conquer Method

- A powerful problem solving technique
- Divide-and-conquer method solves problem in the following steps
  - **Divide step**
    - Divide the large problem into smaller problems
    - Recursively solve the smaller problems
  - **Conquer step**
    - Combine the results of the smaller problems to produce the result of the larger problem

# Divide and Conquer: Merge Sort

- Merge Sort is a divide-and-conquer sorting algorithm
- Divide step
  - Divide the array into two (equal) halves
  - Recursively sort the two halves
- Conquer step
  - Merge the two halves to form a sorted array

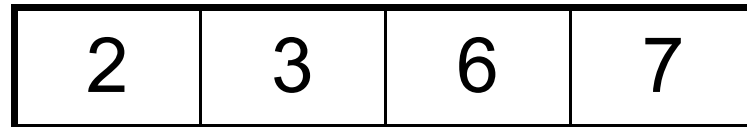
# Merge Sort: Illustration



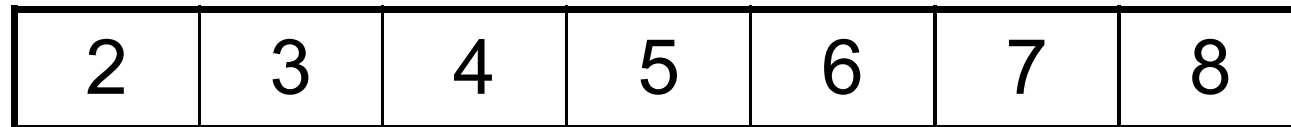
Divide into  
two halves



Recursively  
sort the  
halves



Merge them



## ■ Question

- How should we sort the halves in the 2<sup>nd</sup> step?

# Merge Sort: Implementation

```
void mergeSort(int a[], int low, int high) {  
    if (low < high) {  
        int mid = (low+high) / 2;  
  
        mergeSort(a, low, mid);  
        mergeSort(a, mid+1, high);  
  
        merge(a, low, mid, high);  
    }  
}
```

Merge sort on  
**a[low...high]**

**Divide** a[ ] into two  
halves and **recursively**  
sort them

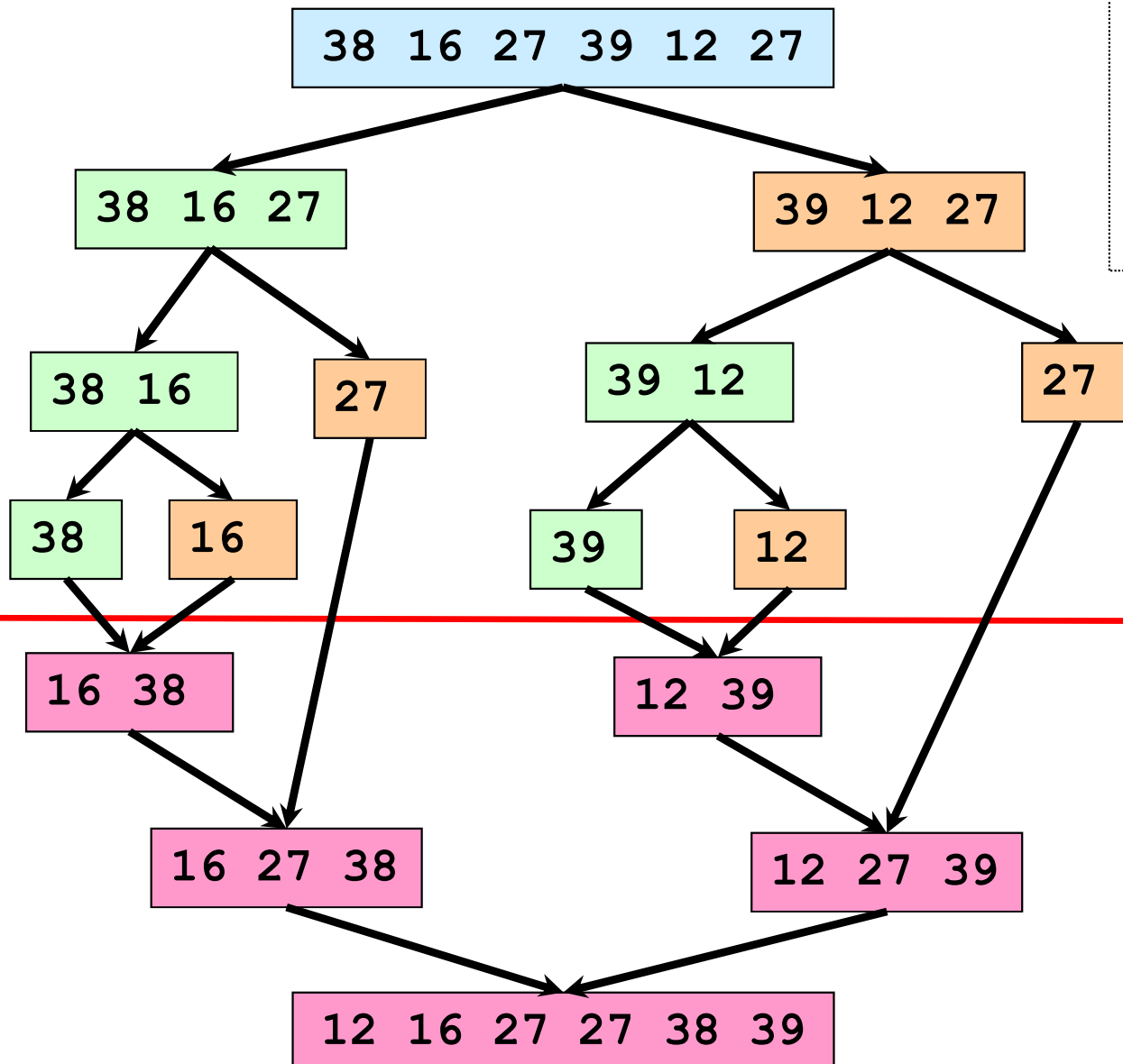
**Conquer:** merge the  
two sorted halves

Function to merge  
**a[low...mid]** and  
**a[mid+1...high]** into  
**a[low...high]**

## ■ Note

- **mergeSort()** is a recursive function
- **low >= high** is the base case, i.e. there is 0 or 1 item

# Merge Sort: Example



```
mergeSort(a[low..mid])  
mergeSort(a[mid+1..high])  
merge(a[low..mid],  
      a[mid+1..high])
```

**Divide Phase**  
Recursive call to  
mergeSort()

**Conquer Phase**  
Merge steps

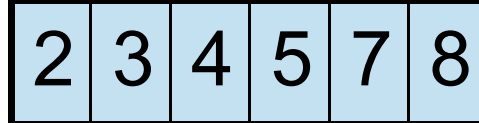
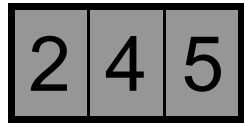
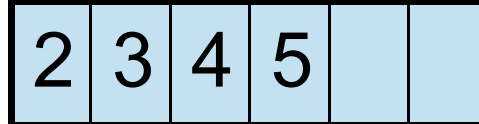
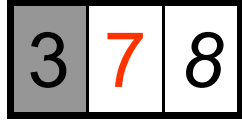
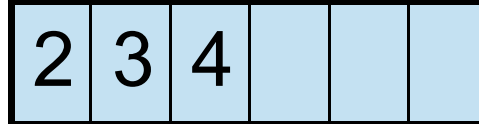
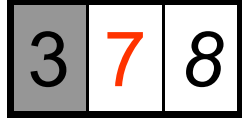
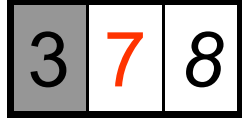
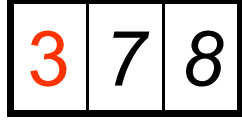
<http://visualgo.net/sorting?create=38,16,27,39,12,27&mode=Merge>

# Merge Sort: Merge

a[0..2]

a[3..5]

b[0..5]



Two sorted halves to be merged

Merged result in a temporary array

x	Unmerged items
x	Items used for comparison
x	Merged items

# Merge Sort: Merge Implementation

PS: C++ STL <algorithm> has [merge](#) subroutine too

```
void merge(int a[], int low, int mid, int high) {
```

```
    int n = high-low+1;
```

```
    int* b = new int[n];
```

```
    int left=low, right=mid+1, bIdx=0;
```

```
    while (left <= mid && right <= high) {
```

```
        if (a[left] <= a[right])
```

```
            b[bIdx++] = a[left++];
```

```
        else
```

```
            b[bIdx++] = a[right++];
```

```
    }
```

```
    // continue on next slide
```

**b** is a temporary array to store result

**Normal Merging**  
Where both halves have unmerged items

# Merge Sort: Merge Implementation

```
// continued from previous slide
```

```
while (left <= mid) b[bIdx++] = a[left++];  
while (right <= high) b[bIdx++] = a[right++];
```

```
for (int k = 0; k < n; k++)  
    a[low+k] = b[k];
```

Merged result  
are copied  
back into **a[]**

Remaining  
items are  
copied into  
**b[]**

```
delete [] b;
```

Remember to free  
allocated memory

## ■ Question

- Why do we need a temporary array **b[]**?



# Merge Sort: Analysis

- In **mergeSort()**, the bulk of work is done in the **merge** step
- For **merge(a, low, mid, high)**
  - Let total items =  $k = (\text{high} - \text{low} + 1)$
  - Number of comparisons  $\leq k - 1$
  - Number of moves from original array to temporary array =  $k$
  - Number of moves from temporary array back to original array =  $k$
- In total, number of operations  $\leq 3k - 1 = O(k)$
- The important question is
  - How many times is **merge()** called?

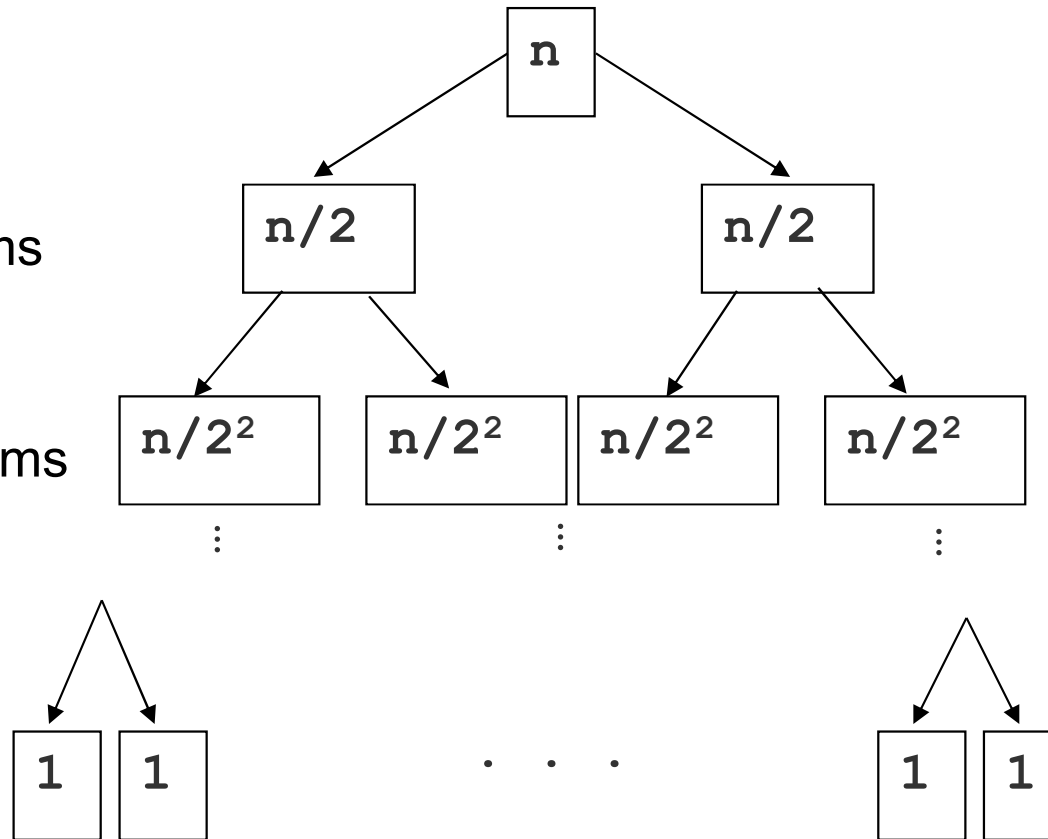
# Merge Sort: Analysis

Level 0:  
mergeSort  $n$  items

Level 1:  
mergeSort  $n/2$  items

Level 2:  
mergeSort  $n/2^2$  items

Level ( $\lg n$ ):  
mergeSort 1 item



Level 0:  
1 call to mergeSort

Level 1:  
2 calls to mergeSort

Level 2:  
 $2^2$  calls to mergeSort

Level ( $\lg n$ ):  
 $2^{\lg n}(= n)$  calls to mergeSort

$$n/(2^k) = 1 \rightarrow n = 2^k \rightarrow k = \lg n$$

# Merge Sort: Analysis

- **Level 0:** **0** call to `merge()`
- **Level 1:** **1** calls to `merge()` with  $n/2$  items in each half,  
 $O(1 \times 2 \times n/2) = O(n)$  time
- **Level 2:** **2** calls to `merge()` with  $n/2^2$  items in each half,  
 $O(2 \times 2 \times n/2^2) = O(n)$  time
- **Level 3:**  **$2^2$**  calls to `merge()` with  $n/2^3$  items in each half,  
 $O(2^2 \times 2 \times n/2^3) = O(n)$  time
- ...
- **Level ( $\lg n$ ):**  $2^{\lg(n) - 1} (= n/2)$  calls to `merge()` with  $n/2^{\lg(n)} (= 1)$  item in each half,  $O(n)$  time
- Total time complexity =  **$O(n \lg(n))$**
- **Optimal** comparison-based sorting method

# Merge Sort: Pros and Cons

## ■ Pros

- The performance is guaranteed, i.e. unaffected by original ordering of the input
- Suitable for extremely large number of inputs
  - Can operate on the input portion by portion

## ■ Cons

- Not easy to implement
- Requires additional storage during merging operation
  - $O(n)$  extra memory storage needed

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# Quick Sort

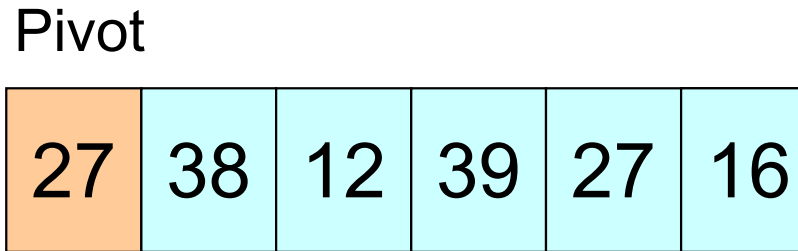
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# Quick Sort: Idea

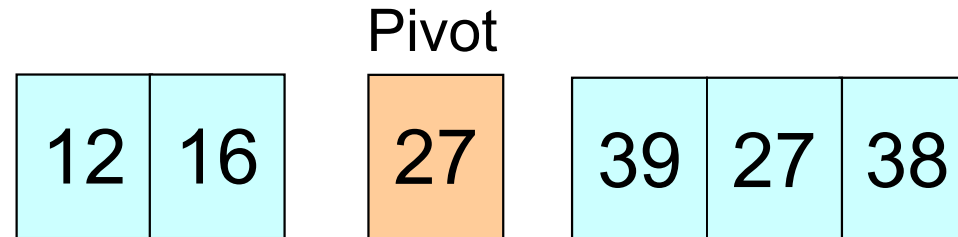
- **Quick Sort** is a divide-and-conquer algorithm
  - **Divide step**
    - Choose an item  $p$  (known as **pivot**) and partition the items of  $a[i..j]$  into two parts
      - Items that are smaller than  $p$
      - Items that are greater than or equal to  $p$
    - Recursively sort the two parts
  - **Conquer step**
    - Do nothing!
- In comparison, **Merge Sort** spends most of the time in conquer step but very little time in divide step

# Quick Sort: Divide Step Example

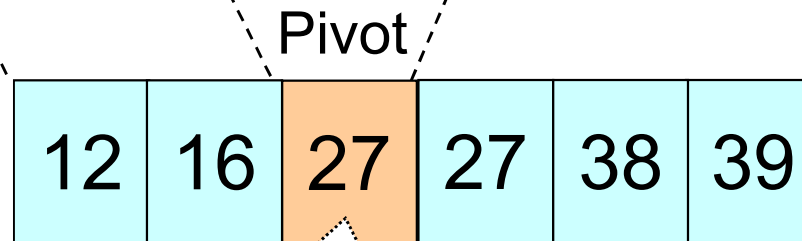
Choose first element as pivot



Partition  $a[]$  about the pivot 27



Recursively sort the two parts



Notice anything special about the position of pivot in the final sorted items?

# Quick Sort: Implementation

```
void quickSort(int a[], int low, int high) {  
    if (low < high) {  
        int pivotIdx = partition(a, low, high)  
  
        quickSort(a, low, pivotIdx-1);  
        quickSort(a, pivotIdx+1, high);  
    }  
}
```

Partition  
**a[low...high]**  
and return the  
index of the  
pivot item

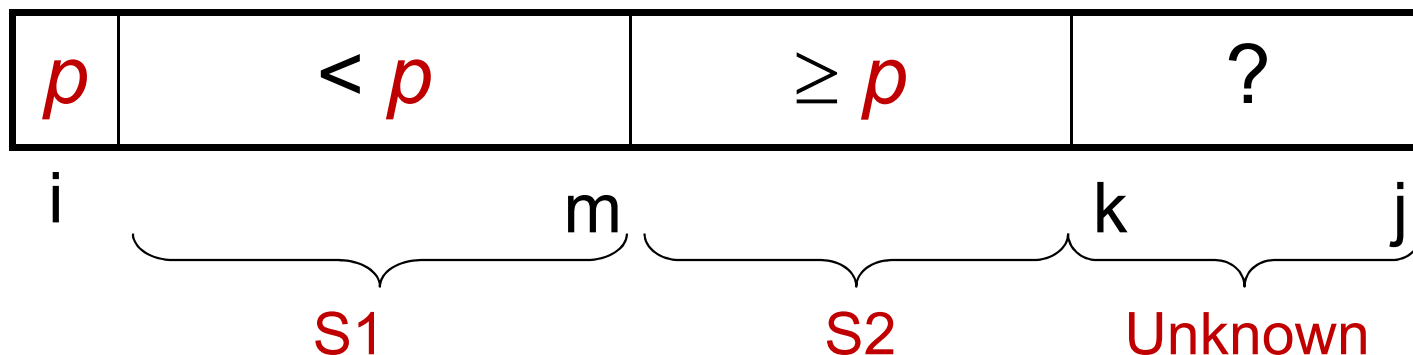
Recursively sort  
the two portions

- **partition()** splits **a[low...high]** into two portions
  - **a[low ... pivot-1]** and **a[pivot+1 ... high]**
- Pivot item does not participate in any further sorting



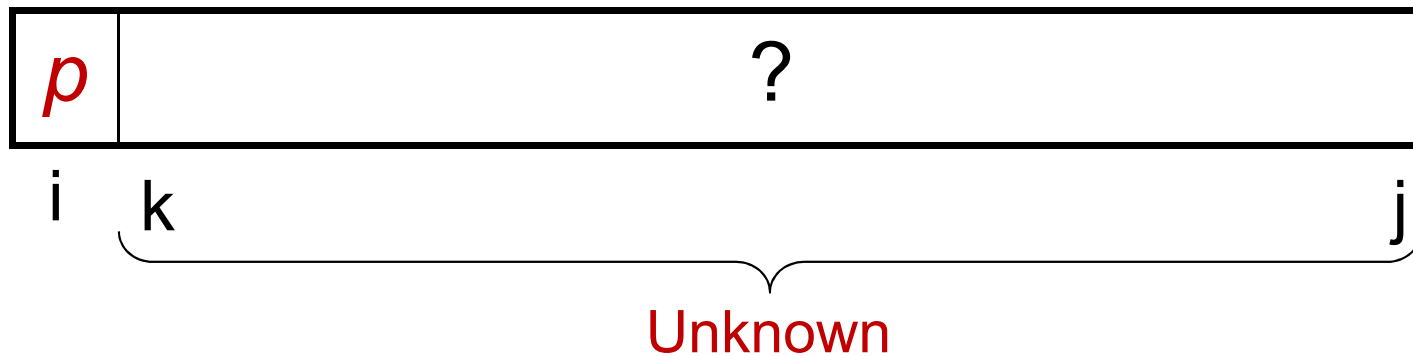
# Quick Sort: Partition Algorithm

- To partition  $a[i...j]$ , we choose  $a[i]$  as the pivot  $p$ 
  - Why choose  $a[i]$ ? Are there other choices?
- The remaining items (i.e.  $a[i+1...j]$ ) are divided into 3 regions
  - **S1** =  $a[i+1...m]$  where items  $< p$
  - **S2** =  $a[m+1...k-1]$  where item  $\geq p$
  - **Unknown** (unprocessed) =  $a[k...j]$ , where items are yet to be assigned to S1 or S2



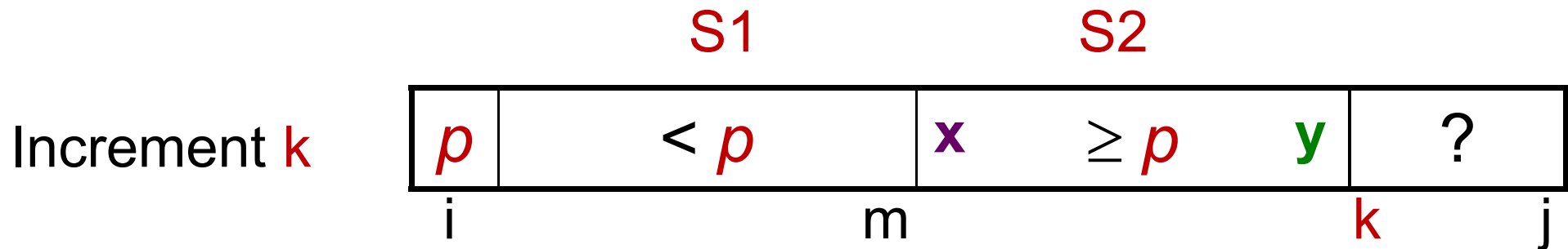
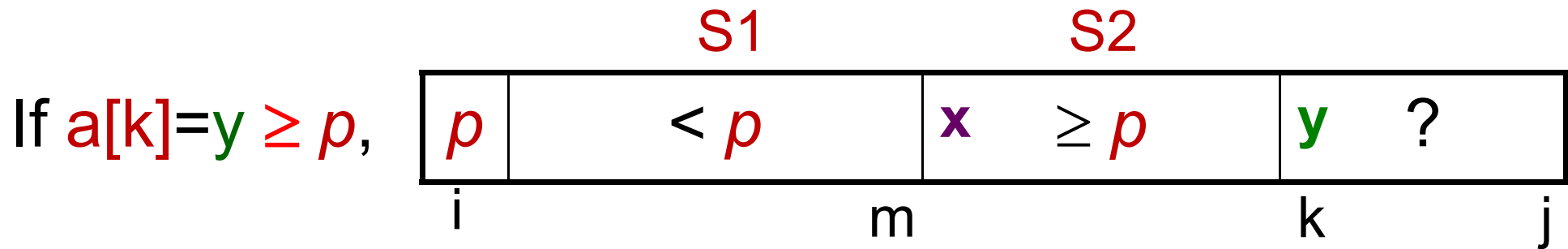
# Quick Sort: Partition Algorithm

- Initially, regions **S1** and **S2** are empty
  - All items excluding  $p$  are in the **unknown** region
- For each item  $a[k]$  in the **unknown** region
  - Compare  $a[k]$  with  $p$ 
    - If  $a[k] \geq p$ , put it into **S2**
    - Otherwise, put  $a[k]$  into **S1**



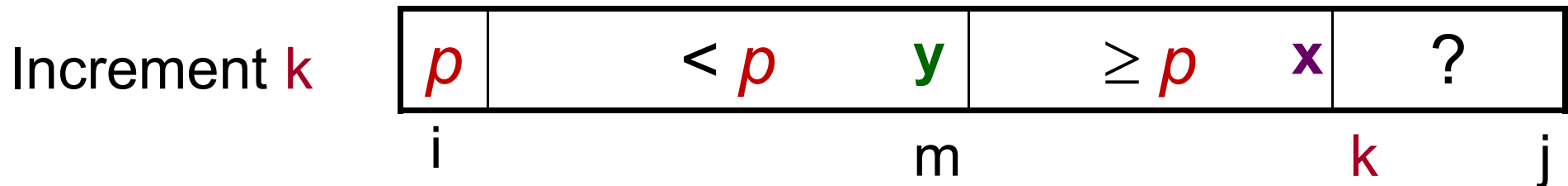
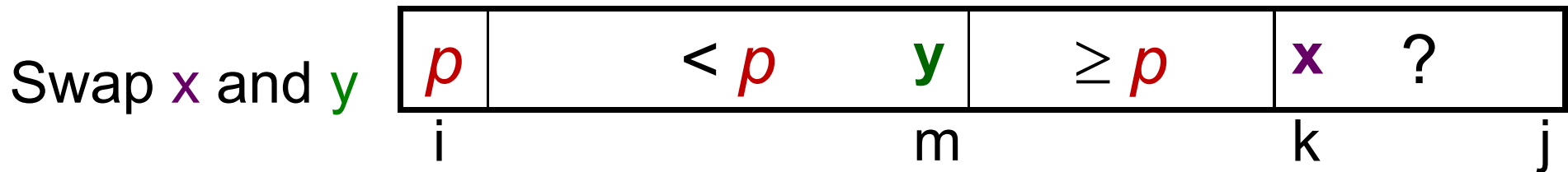
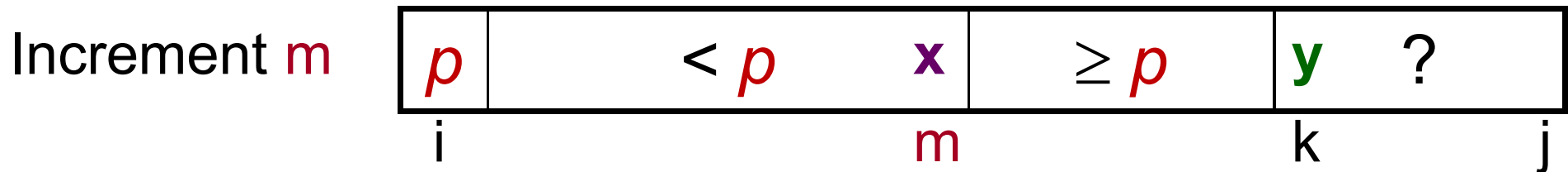
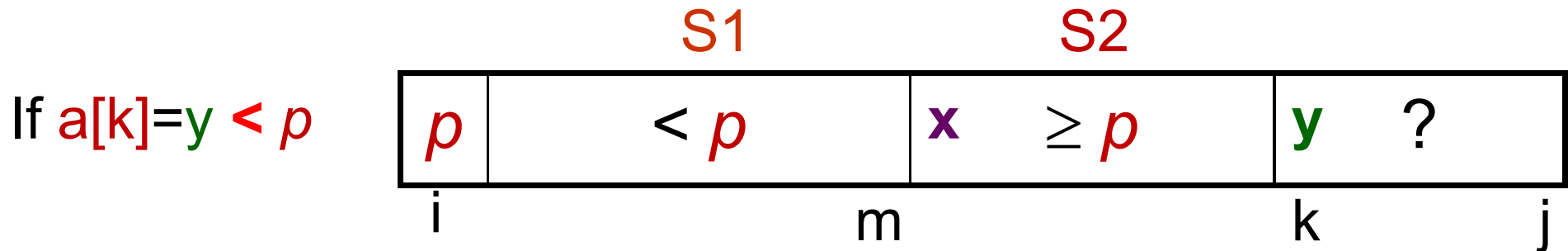
# Quick Sort: Partition Algorithm

- Case 1: if  $a[k] \geq p$



# Quick Sort: Partition Algorithm

- Case 2: if  $a[k] < p$



# Quick Sort: Partition Implementation

PS: C++ STL `<algorithm>` has [partition](#) subroutine too

```
int partition(int a[], int i, int j) {
```

```
    int p = a[i];
```

```
    int m = i;
```

```
    for (int k = i+1; k <= j; k++) {
```

```
        if (a[k] < p) {
```

```
            m++;
```

```
            swap(a[k], a[m]);
```

```
        }
```

```
        else {
```

```
        }
```

```
    }
```

```
    swap(a[i], a[m]);
```

```
    return m;
```

```
}
```

**p** is the pivot

**S1** and **S2** empty initially

Go through each element in unknown region

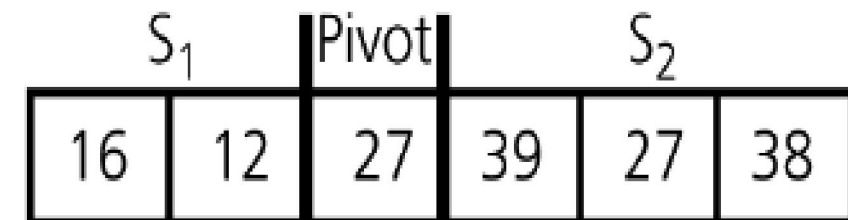
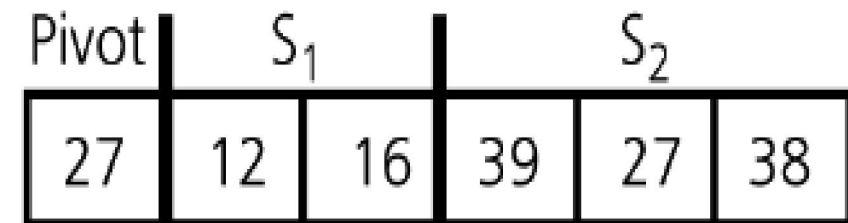
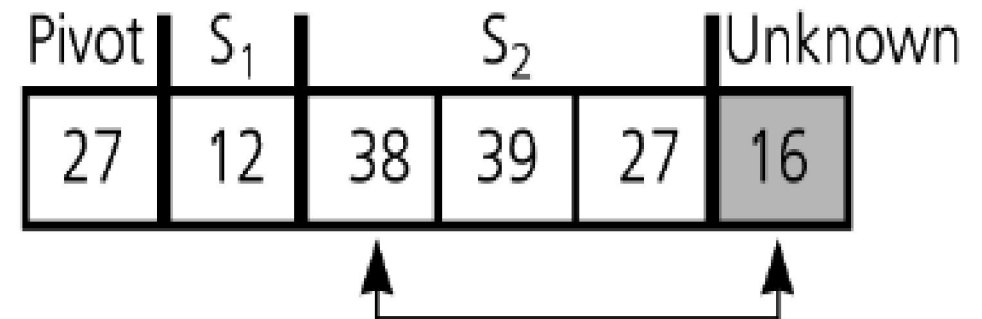
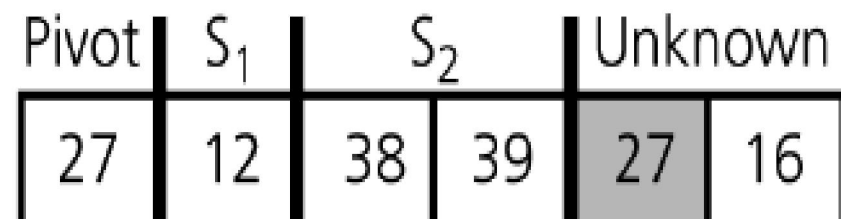
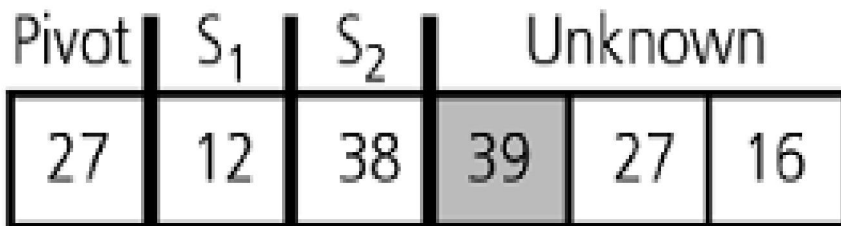
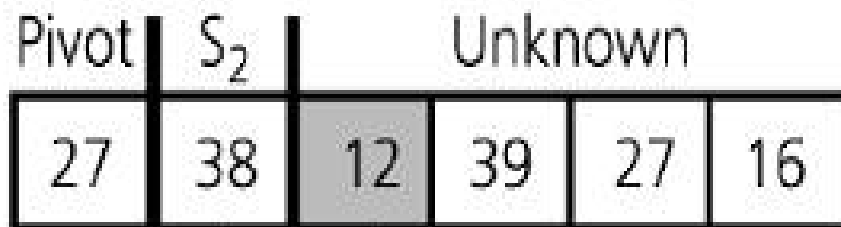
Case 2

Case 1: Do nothing!

Swap pivot with **a[m]**

**m** is the index of pivot

# Quick Sort: Partition Example



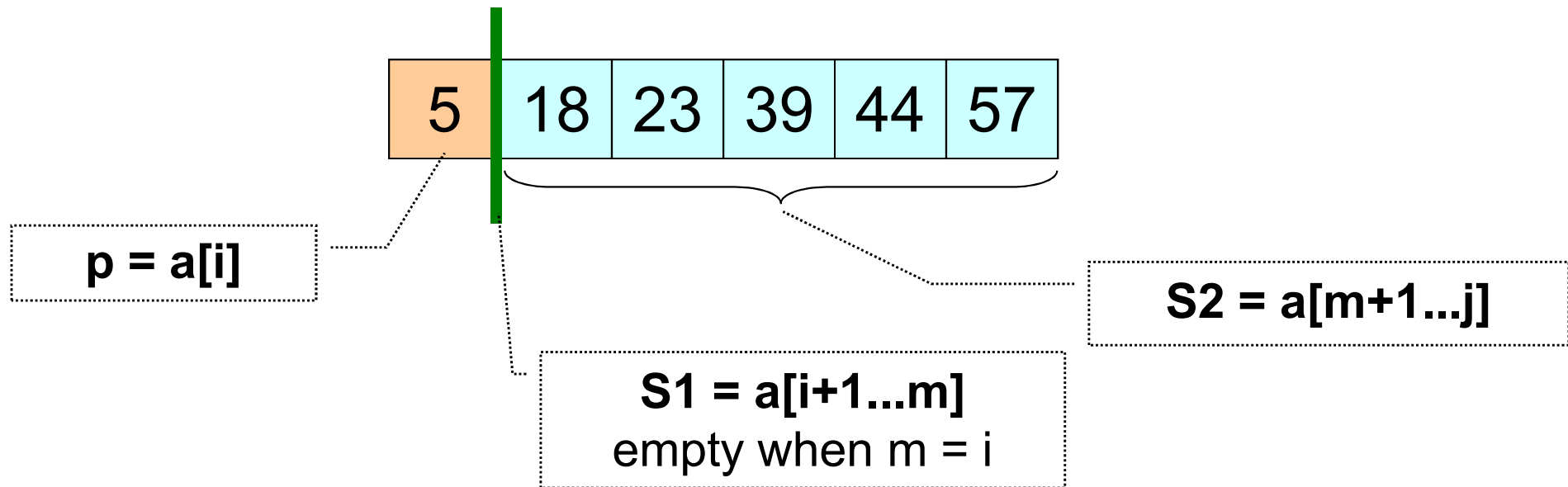
<http://visualgo.net/sorting?create=27,38,12,39,27,16&mode=Quick>

# Quick Sort: Partition Analysis

- There is only a single for-loop
  - Number of iterations = number of items,  $n$ , in the unknown region
    - $n = \text{high} - \text{low}$
  - Complexity is  $O(n)$
  
- Similar to **Merge Sort**, the complexity is then dependent on the number of times **partition()** is called

# Quick Sort: Worst Case Analysis

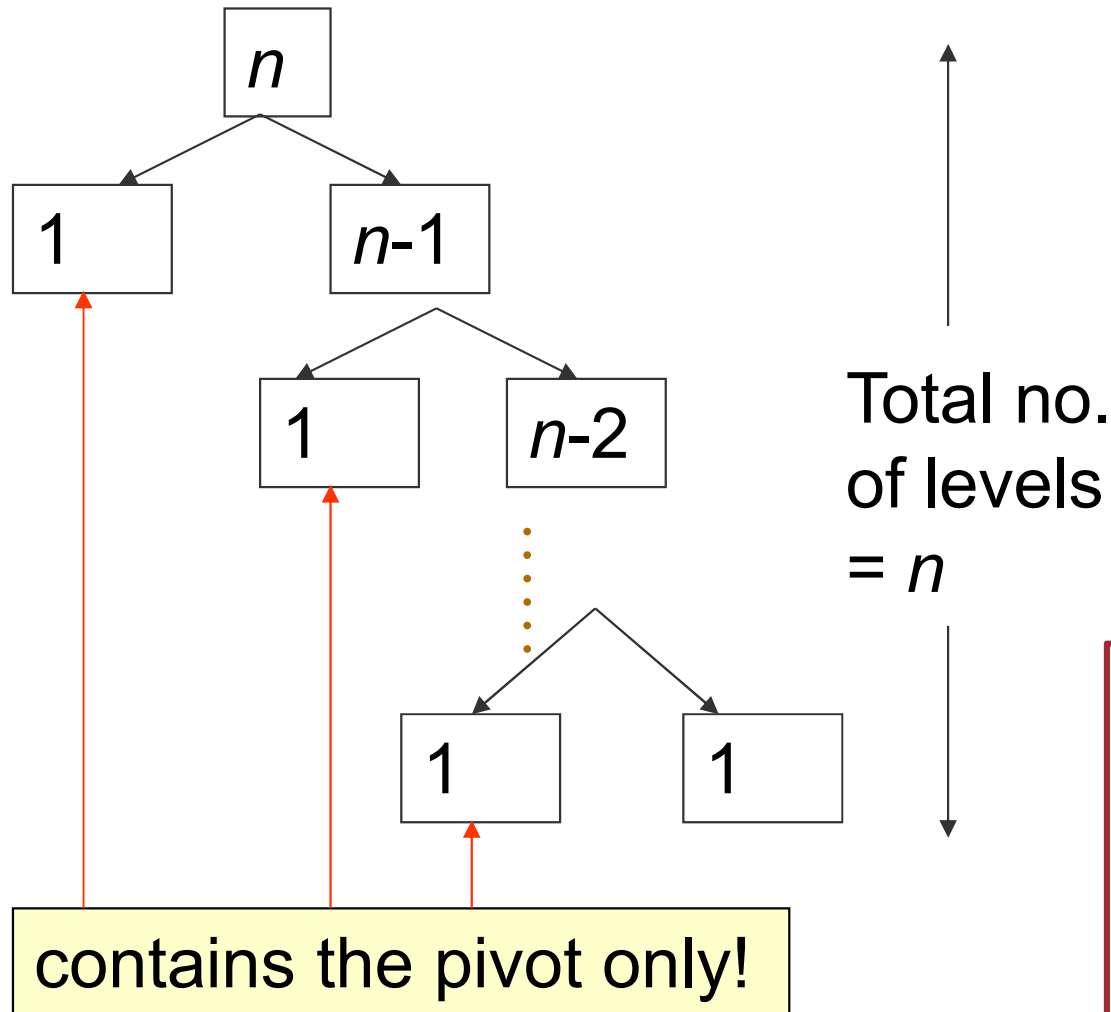
- When the array is already in ascending order



- What is the pivot index returned by **partition()**?
  - What is the effect of **swap(a, i, m)**?
- **S1** is empty, while **S2** contains every item except the pivot



# Quick Sort: Worst Case Analysis



As each partition takes linear time, the algorithm in its worst case has  $n$  levels and hence it takes time  $n+(n-1)+\dots+1 = O(n^2)$

# Quick Sort: Best/Average Case Analysis

- Best case occurs when partition always splits the array into **two equal halves**
  - Depth of recursion is  $\log n$
  - Each level takes  $n$  or fewer comparisons, so the time complexity is  $O(n \log n)$
- In practice, worst case is rare, and on the average we get some good splits and some bad ones (details in CS3230 :O)
  - Average time is also  $O(n \log n)$

# Lower Bound: Comparison-Based Sort

- It is known that
  - All **comparison-based** sorting algorithms have a complexity **lower bound** of  $n \log n$
- Therefore, any comparison-based sorting algorithm with **worst-case complexity**  $O(n \log n)$  is **optimal**

---

# Radix Sort

---

# Radix Sort: Idea

- Treats each data to be sorted as a **character string**
- It is not using comparison, i.e. **no comparison** between the data is needed
- In each iteration
  - Organize the data into groups according to the next character in each data
  - The groups are then “concatenated” for next iteration

# Radix Sort: Example

0123, 2154, 0222, 0004, 0283, 1560, 1061, 2150

Original integers

(156**0**, 215**0**) (106**1**) (022**2**) (012**3**, 028**3**) (215**4**, 000**4**)

Grouped by fourth digit

1560, 2150, 1061, 0222, 0123, 0283, 2154, 0004

Combined

(000**4**) (022**2**, 012**3**) (215**0**, 215**4**) (156**0**, 106**1**) (028**3**)

Grouped by third digit

0004, 0222, 0123, 2150, 2154, 1560, 1061, 0283

Combined

(000**4**, 106**1**) (012**3**, 215**0**, 215**4**) (022**2**, 028**3**) (156**0**)

Grouped by second digit

0004, 1061, 0123, 2150, 2154, 0222, 0283, 1560

Combined

(000**4**, 012**3**, 022**2**, 028**3**) (106**1**, 156**0**) (215**0**, 215**4**)

Grouped by first digit

0004, 0123, 0222, 0283, 1061, 1560, 2150, 2154

Combined (sorted)

# Radix Sort: Implementation

```
void radixSort(vector<int>& v, int d) {  
    int i;  
    int power = 1;  
    queue<int> digitQueue[10];  
  
    for (i = 0; i < d; i++) {  
        distribute(v, digitQueue, power);  
        collect(digitQueue, v);  
        power *= 10;  
    }  
}
```

10 groups. Each is a queue to retain the order of item

- **distribute()**: Organize all items in **v** into groups using digit indicated by the power
- **collect()**: Place items from the groups back into **v**, i.e. “concatenate” the groups

# Radix Sort: Implementation

```
void distribute(vector<int>& v,
               queue<int> digitQ[], int power) {
    int digit;
    for (int i = 0; i < v.size(); i++) {
        digit = (v[i]/power) % 10;
        digitQ[digit].push(v[i]);
    }
}
```

## ■ Question

- How do we extract the digit used for the current grouping?



# Radix Sort: Implementation

```
void collect(queue<int> digitQ[], vector<int>& v) {
    int i = 0, digit;

    for (digit = 0; digit < 10; digit++)
        while (!digitQ[digit].empty()) {
            v[i] = digitQ[digit].front();
            digitQ[digit].pop();
            i++;
        }
}
```

## ■ Basic Idea

- Start with `digitQ[0]`
  - Place all items into vector `v`
- Repeat with `digitQ[1]`, `digitQ[2]`, ...

# Radix Sort: Analysis

- For each iteration
  - We go through each item once to place them into group
  - Then go through them again to concatenate the groups
  - Complexity is  $O(n)$
- Number of iterations is  $d$ , the maximum number of digits (or maximum number of characters)
- Complexity is thus  $O(dn)$

---

# Properties of Sorting

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# In-Place Sorting

- A sort algorithm is said to be an **in-place** sort
  - If it requires only a **constant amount** (i.e.  $O(1)$ ) of **extra space** during the sorting process
- Questions
  - **Merge Sort** is not in-place, why?
  - Is **Quick Sort** in-place?
  - Is **Radix Sort** in-place?

# Stable Sorting

- A sorting algorithm is **stable** if the **relative order of elements with the same key value** is preserved by the algorithm
- Example application of stable sort
  - Assume that **names** have been sorted in alphabetical order
  - Now, if this list is sorted again by **tutorial group number**, a stable sort algorithm would ensure that all students in the same tutorial groups still appear in alphabetical order of their names

# Non-Stable Sort

## ■ Selection Sort

1285 5<sub>a</sub> 4746 602 5<sub>b</sub> (8356)

1285 5<sub>a</sub> 5<sub>b</sub> 602 (4746 8356)

602 5<sub>a</sub> 5<sub>b</sub> (1285 4746 8356)

5<sub>b</sub> 5<sub>a</sub> (602 1285 4746 8356)

## ■ Quick Sort

■ 1285 5<sub>a</sub> 150 4746 602 5<sub>b</sub> 8356 (pivot=1285)

■ 1285 (5<sub>a</sub> 150 602 5<sub>b</sub>) (4746 8356)

■ 5<sub>b</sub> 5<sub>a</sub> 150 602 1285 4746 8356

# Sorting Algorithms: Summary

	Worst Case	Best Case	In-place?	Stable?
Selection Sort	$O(n^2)$	$O(n^2)$	Yes	No
Insertion Sort	$O(n^2)$	$O(n)$	Yes	Yes
Bubble Sort	$O(n^2)$	$O(n^2)$	Yes	Yes
Bubble Sort 2	$O(n^2)$	$O(n)$	Yes	Yes
Merge Sort	$O(n \lg n)$	$O(n \lg n)$	No	Yes
Quick Sort	$O(n^2)$	$O(n \lg n)$	Yes	No
Radix sort	$O(dn)$	$O(dn)$	No	yes

# Summary

- Comparison-Based Sorting Algorithms
  - Iterative Sorting
    - Selection Sort
    - Bubble Sort
    - Insertion Sort
  - Recursive Sorting
    - Merge Sort
    - Quick Sort
- Non-Comparison-Based Sorting Algorithms
  - Radix Sort
- Properties of Sorting Algorithms
  - In-Place
  - Stable